

# Ten Blue Links on Mars

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## ABSTRACT

This paper explores a simple question: How would we provide a high-quality search experience on Mars, where the fundamental physical limit is speed-of-light propagation delays on the order of tens of minutes? On Earth, users are accustomed to nearly instantaneous response times from search engines. Is it possible to overcome orders-of-magnitude longer latency to provide a tolerable user experience on Mars? In this paper, we formulate the searching from Mars problem as a tradeoff between “effort” (waiting for responses from Earth) and “data transfer” (pre-fetching or caching data on Mars). The contribution of our work is articulating this design space and presenting two case studies that explore the effectiveness of baseline techniques, using publicly available data from the TREC Total Recall and Sessions Tracks. We intend for this research problem to be aspirational and inspirational—even if one is not convinced by the premise of Mars colonization, there are Earth-based scenarios such as searching from a rural village in India that share similar constraints, thus making the problem worthy of exploration and attention from researchers.

## 1. INTRODUCTION

Search and other transactional web services strive to minimize response times in order to provide a sense of interactivity and to maintain user engagement. Regardless of how efficiently we implement these services, their response times are limited by roundtrip network latency, which in turn is limited by technical and physical factors, which include the speed of light. For Earth-based users the physical limits imposed by the speed of light amount to less than a second of delay, even when a packet must bounce off a geosynchronous satellite. Consider, however, the case of future colonists on Mars, who will be between 4 and 24 light-minutes away, depending on the relative positions of the two planets.<sup>1</sup> This paper explores a simple question: Is it possible to engineer around physical laws and provide a tolerable search experience from Mars?

While Martian colonies may be a decade or more in the future, plans are being actively developed, with the public support of luminaries such as space entrepreneur Elon Musk [11] and Edwin “Buzz” Aldrin, one of the first two people to walk on the Moon [1]. Both Mars to Stay<sup>2</sup> and Mars One<sup>3</sup>

propose permanent settlements, with colonists potentially living out the remainder of their lives on Mars. While the idea of permanent settlements may seem like science fiction to some, there are substantial cost savings from permanent colonization, as opposed to a traditional Apollo-style there-and-back-again mission, since fuel and other resources for immediate return will not be required. Permanent colonists can conduct more science, over much longer periods, greatly increasing the benefits accrued from the mission.

Current planning assumes that colonists will simply have to tolerate communication delays, limiting their ability to use the Internet. Mars One planners assume communication will be limited to email, video messages, and the like. For other services, they currently assume:

The astronauts can use the Internet, but can only surf “real time” on a number of websites that are downloaded from Earth on the Mars habitat webserver. Every astronaut will have access to his favorite websites that way. Visiting other websites will be a bit impractical because of the delay.<sup>4</sup>

While in the short term our colonists will tolerate whatever is necessary for the success of the mission, a long term separation from digital life on earth need not be one of them. Searching, surfing, and shopping should be as easy from Mars as it is from Marseille.

The primary contribution of this work is an articulation of the design space of how we might engineer search from Mars. We model the problem as a tradeoff between “effort” (waiting for responses from Earth) and “data transfer” (pre-fetching or caching data on Mars). We flesh out our design by considering two concrete tasks using publicly available data: In the first task, we build on a previous short paper [5] and explore high-recall retrieval (such as conducting a scientific survey) using data from the TREC Total Recall Track. In the second task, we simulate interactive search sessions on Mars using data from the TREC Sessions Track. In both cases, our work examines what researchers might call “reasonable baselines”. We readily concede that we do not propose any novel retrieval techniques *per se*—the value of our work lies in formulating a novel problem and laying out the groundwork for future explorations. As such, we hope that our contribution is evaluated in terms of the vision it provides for future research on interplanetary information retrieval.

<sup>1</sup><http://blogs.esa.int/mex/2012/08/05/time-delay-between-mars-and-earth/>

<sup>2</sup><http://www.marstostay.com/>

<sup>3</sup><http://www.mars-one.com/>

<sup>4</sup><http://www.mars-one.com/faq/technology/how-does-the-mars-base-communicate-with-earth>

## 2. BACKGROUND AND RELATED WORK

The problem of searching from Mars is intended to be aspirational as well as inspirational. Even if one remains unconvinced about interplanetary colonization in the short term, our work remains relevant in the same sense that zombie apocalypse preparations advocated by the Centers for Disease Control are instructive.<sup>5</sup> Like that effort, theoretical considerations about unlikely scenarios can lead to insights with more immediate impact. In fact, search from Mars can be thought of as a specific instantiation of what Teevan et al. [20] call “slow search”, which aims to relax latency requirements for a potentially higher-quality search experience. Slow search explores latencies on the order of minutes to hours, which is similar to speed of light propagation delay to Mars. There is substantial precedent for our work, as we discuss below.

Technologies developed for search on Mars have potential applications closer to home in improving search from remote areas on Earth such as Easter Island, where only satellite Internet is available, and the Canadian Arctic, where Internet access remains prohibitively slow and expensive. Our work builds on previous efforts to enhance Internet access in developing regions such as rural India, where connectivity is poor and intermittent. Thies et al. [21] explored web search over email, an interaction model that is not unlike searching from Mars. Chen et al. [4] specifically tackle the problem of search over intermittent connections, attempting to optimize the amount of interaction that a single round of downloading can enable. Intermittent connections can be modeled as high latency, which makes the problem quite similar to ours—and indeed Chen et al. use some of the query expansion and pre-fetching techniques we explore here.

In this work, we assume that a functional interplanetary Internet already exists, and that the only problem we need to overcome is latency at the application layer. This is not an unrealistic assumption as other researchers have been exploring high-latency network links in the context of what is known as delay-tolerant networking (see, for example, IETF RFC 4838<sup>6</sup>) and NASA has already begun experimental deployments on the International Space Station.<sup>7</sup> Once again, there are many similarities between building interplanetary connectivity and enhancing connectivity in developing regions. Examples of the latter include DakNet [17], deploying wifi access points on buses to provide intermittent connectivity to users along their routes and the work of Seth et al. [18] to ferry data using mechanical backhaul (i.e., sneakernet)—which isn’t very different from our proposal to put a cache of the web on a Mars-bound rocket (more details later).

Even if one accepts the premise of Mars colonization, there may remain skepticism about the importance of providing web search. While challenges such as sustaining life, finding appropriate shelter, and extracting energy are no doubt paramount, the psychological health of Martian colonists is important also. As the web has become an integral part of our daily lives, we believe that replicating the experience of the web on Mars is an integral element of maintaining psychological well-being. The HI-SEAS (Hawaii Space Exploration Analog and Simulation) missions and other previous

efforts, which attempt to simulate long-duration habitation on Mars, are a recognition that keeping colonists sane is just as important as keeping them alive.

Having accepted the premise of searching from Mars, let us next flesh out some of the constraints in more detail. There exist technologies built around laser-based communication where it is possible to achieve good bandwidth between Earth and Mars. The Lunar Laser Communications Demonstration achieved a 622-Mbps downlink and a 20-Mbps uplink between the Earth and the Moon,<sup>8</sup> so something like this to Mars is technologically feasible. More bandwidth can be achieved by building more satellites, so we can probably count on “reasonable” bandwidth between Earth and Mars. The other important factor is physical transit time from Earth to Mars on rockets, which we can use as a vehicle for physically delivering a cache of data (i.e., an interplanetary sneakernet). Missions to Mars have taken between 150 and 300 days over the past half century,<sup>9</sup> and without getting into details about orbital mechanics (tradeoffs between transit time, fuel efficiency, and the prevalence of suitable launch windows), it suffices to say physical transport between the two planets will be on the order of months with current rocket technology. Physical transport time defines a “cache invalidation” problem—as whatever data we put on a rocket runs the risk of becoming stale before it arrives on Mars.

This paper builds on two previous papers that have tackled the search from Mars problem. The first is an unrefereed magazine column that to our knowledge is the first articulation of the search from Mars problem [16]. That article articulates the vision, but lacks technical depth. The second is a short paper [5] that empirically examines the high-recall problem, which provide the basis of a more detailed study we describe in Section 4.

## 3. SPACETIME TRADEOFFS

Achievable response times for searching on Mars requires a tradeoff between latency and bandwidth. If the available bandwidth between Earth and Mars is very large, with few restrictions on usage, searching on Mars need be little different than searching on Earth. Mars would maintain a snapshot of the Earth-based portion of the web on local servers (initially delivered by sneakernet), continuously updating it with the help of Earth-based crawlers. Although this cache would still (unavoidably) be 4 to 24 minutes behind Earth, a searcher on Mars would experience no lag. Of course, if a search on Mars leads the searcher to an Earth-based transactional site, or to other dynamic content, that site will still be subjected to response time delays unless it too provides accommodations for extraterrestrial users, an issue we leave for future work.

Unfortunately, maintaining a snapshot of the Earth-based web means that much of the transferred data will go unseen and unused, at least until the colony gains a sizeable population. Furthermore, although details regarding communications technology are far from finalized, we imagine that bandwidth will be limited and must be used parsimoniously. While some bandwidth might be usable for speculative pre-fetching and caching, potentially wasteful usage

<sup>5</sup><http://www.cdc.gov/phpr/zombies.htm>

<sup>6</sup><https://tools.ietf.org/html/rfc4838>

<sup>7</sup>[http://www.nasa.gov/mission\\_pages/station/research/experiments/730.html](http://www.nasa.gov/mission_pages/station/research/experiments/730.html)

<sup>8</sup><http://llcd.gsfc.nasa.gov/>

<sup>9</sup><http://www.universetoday.com/14841/how-longdoes-it-take-to-get-to-mars/>

must be justifiable by potential benefits to the colonists.

At the other extreme in this design space, if available bandwidth between Earth and Mars is very limited, with usage restricted to the most critical purposes, we can do little to improve searching on Mars. Any kind of speculative pre-fetching or caching would waste critical resources. Under these circumstances, our colonists must tolerate the lag, along with the other restrictions of pioneer life.

Since bandwidth limitations are unknown at present, we quantify tradeoffs in terms of two measurable values, both independent of bandwidth:

1. It takes a Martian longer to perform an online task, relative to the time required on Earth. She requires additional time either because she has to wait longer for an interaction to happen, or because she does extra work to complete her task. For example, while waiting for a search result the Martian might work on some unrelated task, or she might continue to peruse the results of a previous search while she waits for the new results to arrive. In this paper, we do not make a strong distinction between waiting and extra work, since both are wasted effort.
2. We can send more data to Mars, relative to the amount of data we would send to a user’s interaction device on Earth. For example, we might send extra search results, web pages, etc. that the user might never actually view. Two possible techniques are to pre-fetch results and to cache a portion of the web on Mars.

We can express the first value as an “effort ratio”,  $E$ , where user effort might be measured in task completion time, or in some proxy, such as number of web pages viewed:

$$E = \frac{\text{user effort required to complete task on Mars}}{\text{user effort required to complete task on Earth}}$$

We express the second value as a “data ratio”,  $D$ , where data volume might be measured in bytes, or in some proxy, such as number of web pages transferred:

$$D = \frac{\text{data transferred to complete task on Mars}}{\text{data transferred to interaction device on Earth}}$$

For interactive web search, there is a tradeoff between  $D$  and  $E$ . If we perform no pre-fetching or caching on Mars, using the search engine exactly as on Earth, we have  $D = 1$  but  $E$  is maximized. If we continuously send a full web crawl to Mars, we get  $E = 1$ , but  $D$  is maximized. On Earth,  $D = 1$  and  $E = 1$  by definition.

On Mars, we trade off one against the other. While  $E$  is determined largely by the distance between the two planets and the number of roundtrip delays required to complete a task,  $D$  may be arbitrarily large, even when little interaction is required. For example, even pre-fetching pages linked from a SERP (see Section 5.2) increases the number of pages transferred by roughly a factor of ten, even if the user only clicks on a few (or no) results.

#### 4. CASE STUDY 1: TOTAL RECALL

As an example of the tradeoffs discussed in the previous section, we revisit a previous study that considered the problem of high-recall tasks, e.g., scientific surveys, in the context of a permanent Martian colony [5]. In this context, the Martian searcher aims to find as much relevant material as possible while minimizing the amount of non-relevant material consumed.

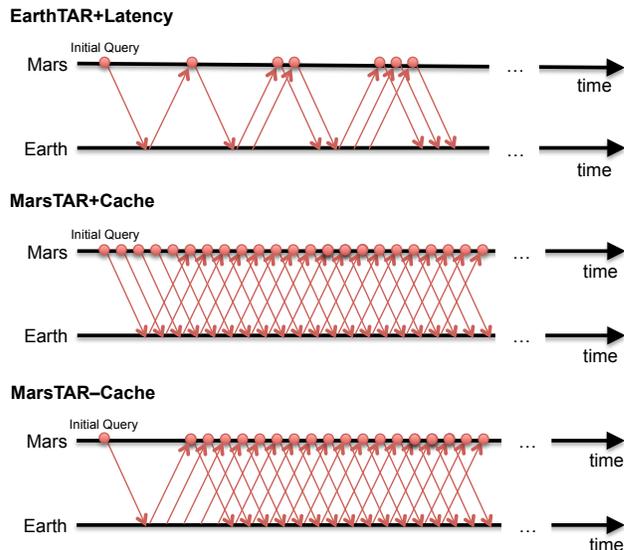


Figure 1: Illustration of various AutoTAR on Mars scenarios. Circles indicate relevance judgments.

The previous study examined this task using Cormack and Grossman’s AutoTAR protocol [7, 9], which uses continuous active learning [6, 8] to iteratively train a classifier based on searcher feedback collected (for computational efficiency) in batches. We omit the details of the underlying algorithm for brevity and encourage interested readers to review the literature.

Four formulations of the AutoTAR protocol were proposed in Clarke et al [5]. As we replicate this previous study using more realistic measurements of time, we provide a brief description of these formulations (See Figure 1):

- **EarthTAR**: The baseline result of running AutoTAR on Earth—the upper bound of performance.
- **EarthTAR+Latency**: The result of running AutoTAR from Mars without any attempts to hide latency, i.e., the searcher waits between batches of new documents from Earth to assess.
- **MarsTAR+Cache**: Two versions of AutoTAR are running, one on Earth and one on Mars. The Martian AutoTAR begins by running on a cache that has been shipped to Mars and is incrementally added to as Earth identifies new potentially-relevant documents that are shipped over to Mars. Earth runs its own version of AutoTAR on the entire collection and is trained by Martian assessments (received after a delay).
- **MarsTAR-Cache**: As above, except there is no pre-existing Martian cache. Thus, after the initial query, the Martian must wait for a roundtrip latency before she can begin assessing documents—these documents are always the ones sent from Earth.

The last three formulations were compared to the EarthTAR upper bound to examine the impact of various roundtrip latencies. As before, we used the Reuters Collection Volume 1 (RCV1) [15], which comes with a fully labeled training and test set split over 103 topics. The training portion, the chronologically first ~24,000 documents of the collection, was used as the Martian cache where applicable. In previous work, we made a simplifying assumption, that

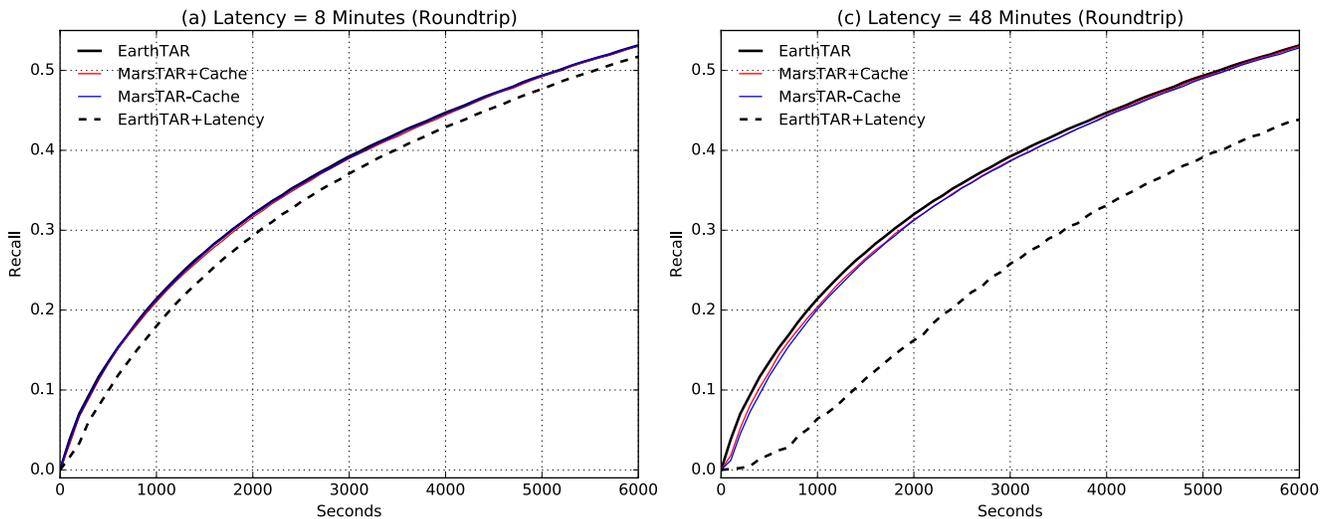


Figure 2: A comparison of the four formulations of AutoTAR with 8 and 48 minute roundtrip delays.

the time to judge a document was one light minute, i.e., in four light-minutes of latency between Earth and Mars, the searcher could judge four documents. Such an assumption makes for easy computation but is not necessarily realistic as it may take seconds to judge a document but minutes to transmit a document. To more accurately model the real scenario, we use Smucker and Clarke’s model [19] of reading speed to calculate time to read and judge a document for our Martian searchers. Their model predicts that for a document with  $l$  words it would take  $0.018l + 7.8$  seconds to read the document.

The assumption that reading time was equivalent to transmission time meant that our previous work used arbitrary latencies between Earth and Mars, ranging from 5 units of time to 500 units of time. In our replication, we use roundtrip latencies of 8 and 48 minutes—these function as minimum and maximum delays that we might expect.

Figure 2 plots the recall achieved as a function of the amount of time spent searching, including any perceived latency, for the two levels of roundtrip latency. These results agree with those reported previously but provide a more accurate picture of what might be conceivably experienced on Mars. It is apparent that a small Martian cache is sufficient to achieve comparable performance with Earth. Even with no cache, Mars is quickly able to “catch up” to Earth-like effectiveness. Furthermore, we note that in the context of high-recall retrieval, there is no wasted transmission. That is, to be sure all relevant material is identified, a searcher must exhaustively examine the entire corpus, regardless of the underlying retrieval protocol, rather than traditional web search where a searcher may examine only one or two documents returned by a SERP. It is worth noting that at any given point in time, the MarsTAR solution may have resulted in additional non-relevant documents being received by Mars when compared to EarthTAR. The plots show, however, that such a discrepancy appears to be relatively small.

## 5. CASE STUDY 2: SEARCH SESSIONS

In our second case study we use an existing query log to examine the impact of searching from Mars and to explore pre-fetching and caching techniques for remediating Earth-Mars latencies. For each search session in our log, we plot

the number of pages transferred to the user’s interaction device against the total time of the session. For searching on Earth, these numbers come directly from the log, since these sessions actually did take place on Earth. For searching on Mars, we add an appropriate delay for each interaction with the search engine. We look particularly at the two extreme cases, an 8-minute delay when the planets are at their closest, and a 48-minute delay when the planets are farthest apart. For this simple simulation, we assume the user waits (or works on some other task) during each interaction cycle.

Academic research into web search is hampered by the paucity of query log data, particularly data for complete search sessions. To address this need, the TREC Session Track created test collections and evaluation measures to study search across multi-query sessions [2, 3, 12–14], as opposed to single-shot queries. As part of this effort, the track organizers gave specific search tasks to recruited users, and recorded queries, clicks, dwell times, and other information as the users conducted these search tasks. The track ran for five years (TREC 2010–2014). We used TREC 2014 data for our experiments [3].

For TREC 2014, track organizers recruited users through Amazon Mechanical Turk, recording 1,257 unique sessions, comprising 4,680 queries and 1,685 clicks. Users conducted searches with the Indri search engine over the ClueWeb12 collection, a crawl of 733 million pages from the general web gathered in early 2012.<sup>10</sup> While the size of this collection is modest by commercial standards, and the size of the log is dwarfed by a few milliseconds of commercial search, it has proven to be a valuable resource for understanding user behavior across sessions [22]. For illustrative purposes, a sample of the log is shown in Figure 3.

### 5.1 Baselines

Earth-based interactions are taken directly from the log, which was naturally recorded on Earth. Figure 4 plots sessions, with each point representing a single session. Session duration is plotted on the  $x$  axis and the number of pages transferred is plotted on the  $y$  axis. For the purposes of counting pages transferred, a SERP counts as a single page and a click counts as a single page.

<sup>10</sup><http://lemurproject.org/clueweb12/>

```

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      <clueweb12id>clueweb12-1304wb-65-15002</clueweb12id>
      <title>Lara Dutta, wrapped in leaves</title>
      <snippet> ... Lara Dutta? No? Lara Dutta is an Indian actress, UNFPA Goodwill Ambassador and former
        Miss Universe 2000, says Wikipedia.lara dutta b 080710 ... </snippet>
    </result>
    <result rank="2">
      <url>\protect\vrule width0pt\protect\href{http://www.missuniverse.com</url>}{http://www.missuniverse.com</url>}
    </result>
  </results>
...

```

Figure 3: Example of TREC 2014 Session Track log data.

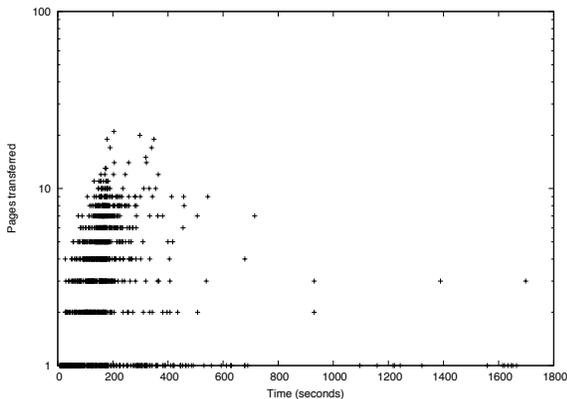


Figure 4: Search Sessions on Earth: Each point indicates the pages transferred and total time for a single session.

Location	Lag (min)	Average time (sec)	Average pages transferred	Effort ratio ( $E$ )	Data ratio ( $D$ )
Earth	0	172.323	3.940	1.000	1.000
Mars	8	2046.118	3.904	15.334	0.995
Mars	48	11415.092	3.904	87.005	0.995

Table 1: Average performance for Earth-based and Mars-based sessions under various delay scenarios, with no pre-fetching or caching.

Points falling along the  $x$  axis represent searches where the user issued only a single query and did not click on any results. Most sessions take under ten minutes, with a few taking nearly a half hour. In these logs, session duration is assumed to start when the user begins to consider the search problem, and not when the first query is issued. We retain this approach in our experiments.

As the simplest simulation of searching from Mars, we can replay the session logs, assuming the user waits (or does other work) after each query and click, while the request is sent to Earth and the response is returned to Mars. Figure 5 plots sessions under minimum and maximum delay times. In these plots, delays clearly dominate interaction times, especially with a worst-case 48 minute delay. These simulations do include some very basic caching. If a query is issued multiple times or if a page is clicked multiple times, we assume the result is fetched only once.

Table 1 shows average transfers and average session dura-

Location	Lag (min)	Average time (sec)	Average pages transferred	Effort ratio ( $E$ )	Data ratio ( $D$ )
Earth	0	172.323	3.940	1.000	1.000
Mars	8	1436.667	23.593	11.263	7.477
Mars	48	7758.385	23.593	62.578	7.477

Table 2: Average performance for Earth-based and Mars-based sessions under various delay scenarios, with SERP pre-fetching.

tion for various scenarios, along with effort ratios ( $E$ ) and data ratios ( $D$ ) as defined in Section 3. Average effort ratio ( $E$ ) essentially grows linearly with roundtrip time, i.e., the lag seen by the user. Data ratio ( $D$ ) actually drops slightly, since we do not assume caching in an Earth-based browser. If we had, we would have  $D = 1$  in all cases.

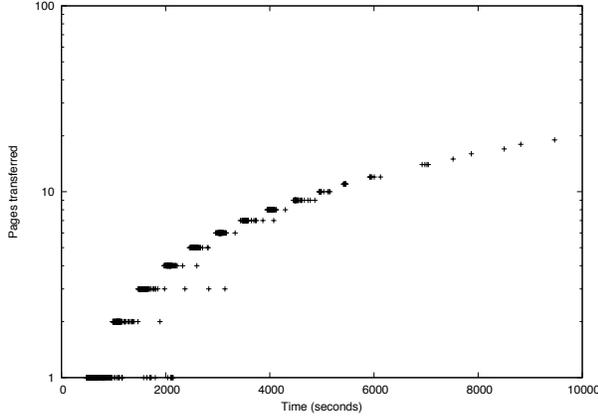
## 5.2 Pre-fetching

How might we begin to hide latencies associated with searching from Mars? After the initial query in a session, we might attempt to predict the user’s needs and pre-fetch pages required for the remainder of the session, potentially reducing  $E$  at the cost of an increase in  $D$ . We try three simple approaches: pre-fetching pages linked directly from SERPs (up to ten), pre-fetching additional related pages (perhaps several thousand) along with the pages linked from SERPs, and expanding with query suggestions and returning associated SERP pages.

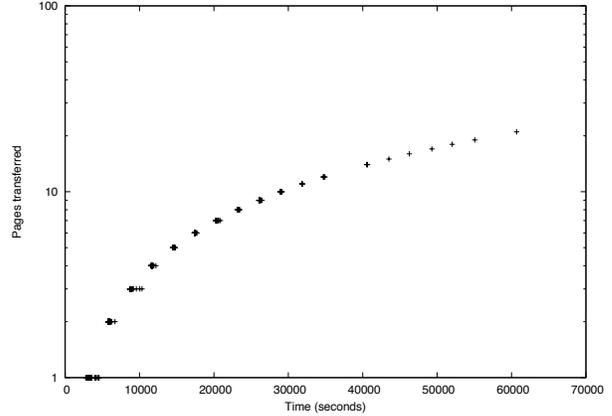
**SERP Pre-fetching.** As our first attempt at pre-fetching to reduce  $E$ , we pre-fetch result pages linked from SERPs, under the assumption that the user will click on at least some of them. Indeed, pre-fetching of result pages is so obviously sensible that we cannot imagine supporting search on Mars without at least this form of pre-fetching, unless bandwidth limitations are extremely severe. Here, we pre-fetch only the pages directly linked from SERPs in the logs, but we might imagine going further, perhaps by loading more of the linked site or by pre-fetching deeper in the result list.

Figure 6 plots individual sessions using SERP pre-fetching, while Table 2 shows average effort and data ratios. While most SERPs in our query log link to ten pages,  $D$  is less than 10 due to caching effects.  $E$  increases linearly with lag, but values are at 25% or more below those in Table 1. That is, we save around 25% effort at the cost of transferring around around seven times more data than necessary.

**Topical Pre-fetching.** A simple way to extend SERP pre-fetching would be to go deeper in the ranked list, perhaps

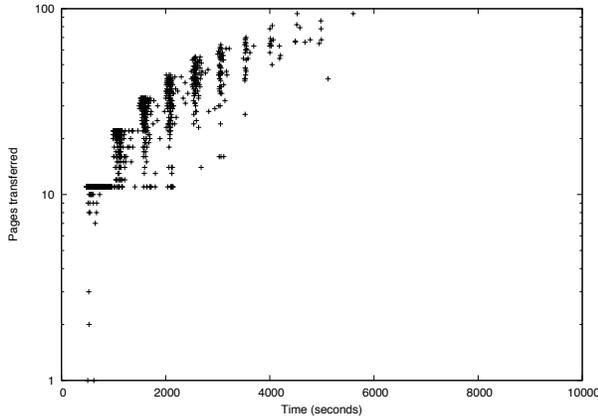


(a) 8 minute response time

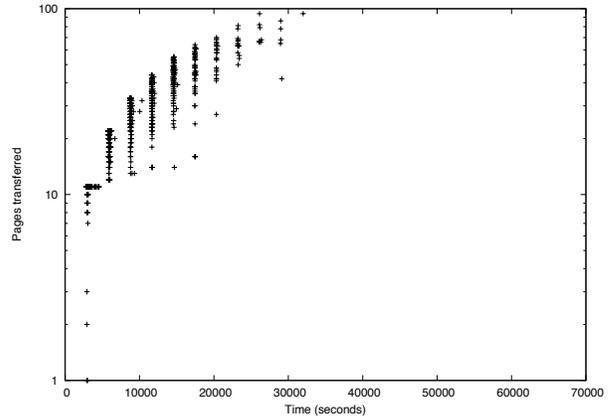


(b) 48 minute response time

Figure 5: Search Sessions on Mars: Each point represents a single session with no pre-fetching or caching.



(a) 8 minute response time



(b) 48 minute response time

Figure 6: Search Sessions on Mars: Each point represents a single session with SERP pre-fetching.

uploading a large set of topically related pages in response to each query, along with the pages linked directly from the SERP. Even when a Martian user issues a further query, requiring another roundtrip delay, these pages would allow the user to further explore their topic while awaiting additional results from Earth. If large numbers of related pages are uploaded, query reformulations can also be issued against these local pages, perhaps allowing the Martian to satisfy their information need without waiting.

To explore the potential for topical pre-fetching, we indexed the ClueWeb12 collection using the Lucene search engine. As queries appear in the log, we execute them against this index using BM25. We then assume that the top  $k$  documents are sent to Mars, along with documents linked from the SERP. Since we are using different search tools (and ranking algorithm) from those used by the TREC Session Track, not all pages from the SERPs appear in our top  $k$ . In reality, of course, the SERP documents would be the top-ranked subset of our top  $k$ , so that exactly  $k$  documents would be transferred to Mars.

We consider hits on these uploaded documents, where we count as a hit any topically pre-fetched document that later appears in a SERP from the same session. Having these

pages already on Mars potentially allows the Martian user to access them without having to wait for the SERP in which they first appear. With  $k = 1000$  we achieve a hit ratio of over 21%; with  $k = 2000$  we achieve a hit ratio of over 27%. These hit ratios should translate into substantial reductions in  $E$ , although a reasonable estimate requires many assumptions about user behavior, which we avoid in this paper. Unfortunately, this potential improvement to  $E$  comes at a cost in  $D$ , as compared to SERP pre-fetching alone, since  $D$  is approximately equal to  $k$ . That is, we marginally improve effort at a great cost in transferring data that is never used.

**Query Suggestions.** Most commercial search engines suggest query reformulations and extensions to help guide their users through search sessions. We might take advantage of these suggestions by executing them on behalf of the Martian user, uploading the results and their linked pages, along with the main SERP and its linked pages. If a reformulation by a Martian user matches a query suggestion, we completely avoid a query-response cycle to Earth, even if the Martian makes an unanticipated reformulation, the additional uploaded information might allow her to continue working while waiting for a response from Earth.

To explore the potential of this idea, we submitted queries from our log to the Bing Autosuggest API<sup>11</sup> and compared suggestions to queries appearing later in the same session. For 57 queries, a suggested query appeared verbatim later in the same session. While this is less than 2% of all possible queries, it is clear that the idea has some potential, perhaps by going deeper in the suggestion list or by extracting related terms from suggested queries. While some of the suggestions are spelling corrections or simple morphological variants, some are more complex, e.g., “uglai recipe” for “kenya cooking”.

Combining our various query pre-fetching ideas may provide a reasonable overall solution. When a query is received from Mars, we might imagine expanding it with terms from query suggestions, and through other expansion methods, we could generate a large set of related documents to transmit to Mars for re-ranking and exploration by the Martian user. We might even stream documents continuously, similar to Section 4, adjusting the stream on the basis of queries and other feedback from Mars. We leave the investigation of such ideas for future work.

### 5.3 Caching

As an alternative or in addition to pre-fetching, we could minimize user effort by (partially) caching a snapshot of the web on Mars (we discuss the possible logistics below). If we maintain a partial snapshot on Mars, perhaps we could serve most of the user traffic from that cache, or at the very least give the user some preliminary results to work with while we are fetching full results. But of course, much of the web consists of lower quality pages that would rarely appear in a SERP, and would even more rarely receive a click—the question, of course, is which parts of the web do we send over to Mars? Caching will greatly increase  $D$ , but if the pages are selected based on some type of static rank, or “page quality”, we may be able to reduce  $E$ .

The experiments in this paper used the ClueWeb12 crawl and TREC session logs. Despite possible concerns about the realism and fidelity of the data, we nevertheless can still gain some insight regarding the value of caching.

For static ranking, we use the method of Cormack et al [10], which has performed well on ClueWeb collections (the source of the Waterloo spam scores that are widely used by academic researchers) and has fast code available. Static ranking is based on content only. We trained over the ClueWeb09 collection—an earlier crawl gathered by the same group at CMU in 2009—using as training labels TREC relevance assessments created as part of various experiments using that collection. More specifically, we trained on: 1) all documents judged relevant for any purpose (e.g., for any query) regardless of grade, which were taken as positive examples; 2) all documents assessed as spam, which were taken as negative examples; and 3) a random sample ( $N = 3000$ ) of documents judged as non-relevant, which was also taken as negative examples. The static ranker was then applied to all pages in ClueWeb12. Note that training data is completely disjoint from this collection, and so there is no “information leakage” from the session data.

Based on this static ranking, we might cache a fraction of available pages on Mars. Figure 7 shows hit ratios for cached pages appearing in the log, considering either all pages linked

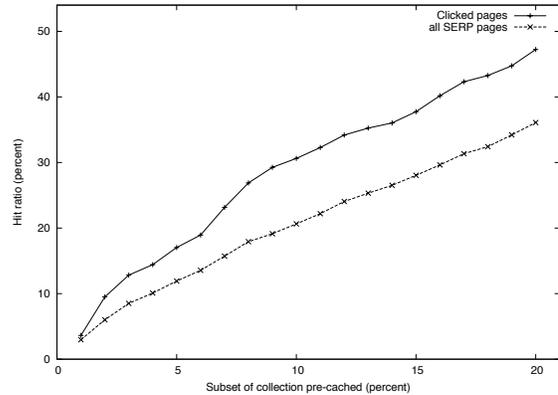


Figure 7: Cache hit ratios for clicked pages and for all SERP result pages.

from SERPs or just pages that were actually clicked. Hit ratios are shown for various caching ratios between 1% and 20% of the full collection. The hit ratio for clicked pages is substantially higher than that for SERP pages generally, helping to confirm the success of our static ranking. By maintaining a 20% snapshot on Mars, we can achieve a hit ratio for clicked pages of nearly 50%.

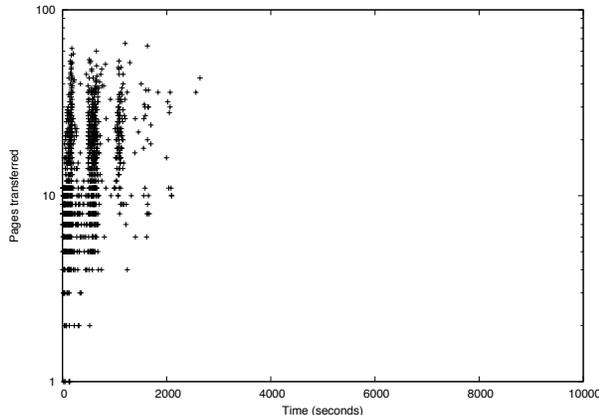
To simulate the impact of caching pages on Mars, we require some assumptions about user behavior in addition to the actual behavior captured in the log. Each session starts as usual, with the user issuing the query appearing in the log. The query is sent to Earth, which follows the SERP pre-fetching approach in Section 5.2, returning the SERP itself and all pages linked from the SERP that are not already on Mars. Meanwhile, the query is also sent to the local cache, which we assume returns a SERP covering the pages in the cache. The user interacts with this local SERP until the log shows she would have clicked on a result not present in the local cache. At that point our simulated user waits for the full Earth-generated SERP before proceeding.

If the user issues further queries, we follow the same process, sending the query to Earth and allowing the user to interact locally without delay. Delay occurs only when the log shows a click on a result not present in the local cache. While the Mars-based user would not actually be able to click on non-local results, since they would not appear on the locally generated SERP, we take the click as a signal of dissatisfaction with the local result. Since we have no way of knowing how the real user would have proceeded, waiting for the Earth-based results provides a worst-case assumption that places an upper bound on  $E$ .

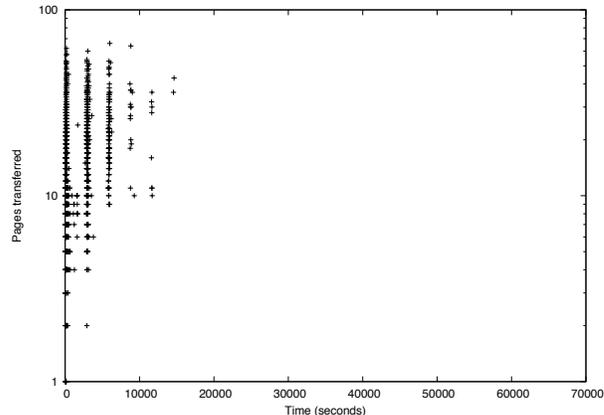
Figure 8 plots the results of this simulation with 20% caching. Here the  $y$  axis shows only pages transferred beyond those already cached. Compared with Figures 5 and 6, overall session times are substantially reduced, although they are still well above the Earth-based times in Figure 4. Average performance appears in Table 3; average pages transferred and data ratios exclude the 157 million cached pages.

How might we actually cache a snapshot of the web on Mars? While in our simulations, 20% of the collection represents a “mere” 157 million pages, 20% of *the entire web* remains a substantial, even daunting amount of data. The most practical approach is to physically transport the cached data on cargo rockets (i.e., a sneakernet). The problem, of course, is the transit time: many of the pages will already

<sup>11</sup><https://www.microsoft.com/cognitive-services/en-us/bing-autosuggest-api>



(a) 8 minute response time



(b) 48 minute response time

Figure 8: Search Sessions on Mars: Each point represents a single session with SERP pre-fetching and 20% caching. The range of the  $x$  axis is the same as Figures 5 and 6. Pages transferred exclude pages in the cache.

Location	Lag (min)	Average time (sec)	Average pages transferred	Effort ratio ( $E$ )	Data ratio ( $D$ )
Earth	0	172.323	3.940	1.000	1.000
Mars	8	445.918	16.351	2.812	5.148
Mars	48	1936.334	16.351	12.561	5.148

Table 3: Average performance for Earth-based and Mars-based sessions under various delay scenarios, with SERP pre-fetching and 20% caching. Average pages transferred and data ratios exclude the 157 million cached pages.

have changed by the time the cache arrives at Mars. Physical transport of data needs to be accompanied by updates sent from Earth—which of course consumes valuable bandwidth. Without updates, searchers on Mars would be interacting with a copy of the web that is several months old.

The combination of sneakernet and incremental updates frames an optimization problem that commercial web search engines are equipped to solve. Today, they must decide what and how frequently to recrawl existing content, and as a result have detailed historic data indicating which pages are “stable” and which pages change rapidly. With this information, it is possible to trade off physical data transport with bandwidth-consuming updates. Although we do not have access to this information, it is a matter of engineering to figure out the best solution. This is a solvable problem.

## 6. CONCLUSIONS AND FUTURE WORK

In this paper, we provide a framework for evaluating search from Mars as a tradeoff between “effort” (waiting for responses from Earth) and “data transfer” (pre-fetching or caching data on Mars). The contribution of our work is articulating this design space and presenting two case studies that explore the effectiveness of baseline techniques. Although we do not present any novel retrieval techniques, tackling the problem must begin with “obvious” solutions. We find, indeed that we can trade off effort with the amount of data transferred, with varying degrees. These simple techniques set the groundwork for future studies.

As we noted earlier, the problem of searching from Mars has analogs closer to home. Instead of a cache we ship to

Mars on a cargo rocket, we might FedEx hard drives of web data to rural villages in the developing world, where the village elders can plug these caches into the central wifi access point. This shared access point can intercept web searches with the local cache; usage log data can determine the pages that arrive on next month’s hard drive shipment. This scenario parallels exactly search from Mars, and thus searching from Mars is more than idle blue-sky speculation. Furthermore, the breakthroughs that are needed—for example, better session models and models of long-term user needs—stand to benefit web search in general.

Moving forward, we continue to consider the larger problem of supporting access to web and social media services on Mars. In the medium term, we hope to establish a full simulation of interaction from Mars, allowing for the creation and testing of a full stack built on top of appropriate high-latency networking technology. Our goal is to create a fully tested and ready-to-go solution for use by future colonists. Exploration is perhaps one of the most innate human drives, and since we’re not rocket scientists, structural engineers, geologists, or botanists, there are limited contributions we can make that are on the “critical path” of sending humans to Mars. However, as information retrieval researchers we can contribute information access solutions for humankind’s next great leap.

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